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Discrete-Time Control Systems by Katsuhiko Ogata

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). 3 + - r(t) e(t) ADC μP DAC u(t) Plant ? ? y(t) 4

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Notes for Discrete-Time Control Systems (ECE-520) Fall 2010 by R. Throne The major sources for these notes are † Modern Control Systems, by Brogan, Prentice-Hall, 1991. † Discrete-Time Control Systems, by Ogata. Prentice-Hall, 1995. † Computer Controlled Systems, by "Astr~om and Wittenmark. Prentice-Hall, 1997.

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Discrete Time Control Systems Ogata Pdf.pdf - Free Download Figure 2: Discrete-time control system b) It is generally advisable to have the crossover frequency of the loop gain centered between the crossover frequencies of the disturbance and the noise, which is at approximately 8rad/s. Also, the control system should be at least one

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